

# Interplay between Gravity and Quantum Physics from the Point of View of General Local Covariance

Katarzyna Rejzner

INdAM (Marie Curie) fellow  
University of Rome Tor Vergata

Rome, 11.07.2013

# Outline of the talk

- 1 Introduction
  - Outline of the program
  - Local covariance
- 2 General relativity: classical theory
  - Basic structures
  - BV complex
- 3 Quantization
  - Deformation quantization
  - Background independence

## This talk is based on:

- R. Brunetti, K. Fredenhagen, K. R.,  
*Quantum gravity from the point of  
view of locally covariant quantum  
field theory*,  
[arXiv:math-ph/1306.1058]

## This talk is based on:

- R. Brunetti, K. Fredenhagen, K. R.,  
*Quantum gravity from the point of view of locally covariant quantum field theory*,  
[arXiv:math-ph/1306.1058]
- ... dedicated to Roberto Longo on the occasion of his 60th Birthday.



## This talk is based on:

- R. Brunetti, K. Fredenhagen, K. R.,  
*Quantum gravity from the point of view of locally covariant quantum field theory*,  
[arXiv:math-ph/1306.1058]
- ... dedicated to Roberto Longo on the occasion of his 60th Birthday.
- **Tanti Auguri Roberto!**



# A new way to quantum gravity?



# A new way to quantum gravity?



Our results:

# A new way to quantum gravity?



## Our results:

- We have formulated perturbative quantum gravity as an effective theory that is valid in given physical situations.
- We proposed a notion of gauge invariant physical quantities of GR and gave a prescription how to quantize such objects.



# A new way to quantum gravity?



## Our results:

- We have formulated perturbative quantum gravity as an effective theory that is valid in given physical situations.
- We proposed a notion of gauge invariant physical quantities of GR and gave a prescription how to quantize such objects.

# A new way to quantum gravity?



## Our results:

- We have formulated perturbative quantum gravity as an effective theory that is valid in given physical situations.
- We proposed a notion of gauge invariant physical quantities of GR and gave a prescription how to quantize such objects.

## The road ahead of us:

# A new way to quantum gravity?



Our results:

- We have formulated perturbative quantum gravity as an effective theory that is valid in given physical situations.
- We proposed a notion of gauge invariant physical quantities of GR and gave a prescription how to quantize such objects.

The road ahead of us:

- Answer some interpretational questions.

# A new way to quantum gravity?



## Our results:

- We have formulated perturbative quantum gravity as an effective theory that is valid in given physical situations.
- We proposed a notion of gauge invariant physical quantities of GR and gave a prescription how to quantize such objects.

## The road ahead of us:

- Answer some interpretational questions.
- **Find a relation to experiment: QG corrections to some processes, black hole radiation, cosmology.**

# A new way to quantum gravity?



## Our results:

- We have formulated perturbative quantum gravity as an effective theory that is valid in given physical situations.
- We proposed a notion of gauge invariant physical quantities of GR and gave a prescription how to quantize such objects.

## The road ahead of us:

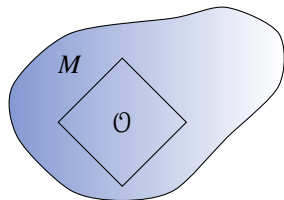
- Answer some interpretational questions.
- Find a relation to experiment: QG corrections to some processes, black hole radiation, cosmology.
- **Understand the small scale structure of spacetime: relation to NCG.**

## Intuitive idea

- In experiment, geometric structure is probed by local observations. We have the following data:

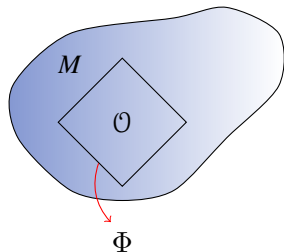
# Intuitive idea

- In experiment, geometric structure is probed by local observations. We have the following data:
  - Compact causally convex region  $\mathcal{O}$  of spacetime where the measurement is performed,



# Intuitive idea

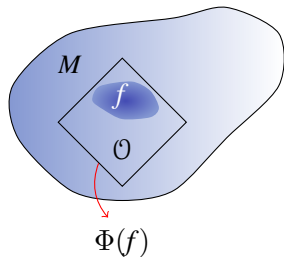
- In experiment, geometric structure is probed by local observations. We have the following data:
  - Compact causally convex region  $\mathcal{O}$  of spacetime where the measurement is performed,
  - An observable  $\Phi$ , which we measure,





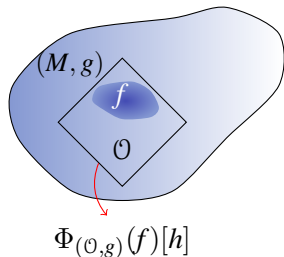
# Intuitive idea

- In experiment, geometric structure is probed by local observations. We have the following data:
  - Compact causally convex region  $\mathcal{O}$  of spacetime where the measurement is performed,
  - An observable  $\Phi$ , which we measure,
  - We don't measure the scalar curvature at a point, but we have some smearing related to the experimental setting:  $\Phi(f) = \int f(x)R(x)$ ,  $\text{supp}(f) \subset \mathcal{O}$ .



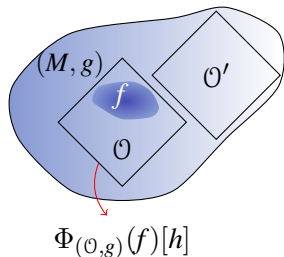
## Intuitive idea

- In experiment, geometric structure is probed by local observations. We have the following data:
  - Compact causally convex region  $\mathcal{O}$  of spacetime where the measurement is performed,
  - An observable  $\Phi$ , which we measure,
  - We don't measure the scalar curvature at a point, but we have some smearing related to the experimental setting:  $\Phi(f) = \int f(x)R(x)$ ,  $\text{supp}(f) \subset \mathcal{O}$ .
- We can think of the measured observable as a perturbation of the fixed background metric: a tentative split into:  $\tilde{g}_{\mu\nu} = g_{\mu\nu} + h_{\mu\nu}$ .



## Intuitive idea

- In experiment, geometric structure is probed by local observations. We have the following data:
  - Compact causally convex region  $\mathcal{O}$  of spacetime where the measurement is performed,
  - An observable  $\Phi$ , which we measure,
  - We don't measure the scalar curvature at a point, but we have some smearing related to the experimental setting:  $\Phi(f) = \int f(x)R(x)$ ,  $\text{supp}(f) \subset \mathcal{O}$ .
- We can think of the measured observable as a perturbation of the fixed background metric: a tentative split into:  $\tilde{g}_{\mu\nu} = g_{\mu\nu} + h_{\mu\nu}$ .
- Diffeomorphism transformation: move our experimental setup to a different region  $\mathcal{O}'$ .

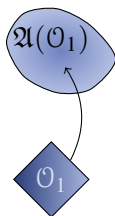


# Algebraic quantum field theory (locality)

- A convenient framework to investigate conceptual problems in QFT is the **Algebraic Quantum Field Theory**.

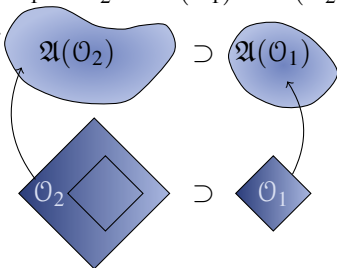
# Algebraic quantum field theory (locality)

- A convenient framework to investigate conceptual problems in QFT is the **Algebraic Quantum Field Theory**.
- It started as the axiomatic framework of **Haag-Kastler**: a model is defined by associating to each region  $\mathcal{O}$  of Minkowski spacetime an algebra  $\mathfrak{A}(\mathcal{O})$  of observables (a unital  **$C^*$ -algebra**) that can be measured in  $\mathcal{O}$ .



# Algebraic quantum field theory (locality)

- A convenient framework to investigate conceptual problems in QFT is the **Algebraic Quantum Field Theory**.
- It started as the axiomatic framework of **Haag-Kastler**: a model is defined by associating to each region  $\mathcal{O}$  of Minkowski spacetime an algebra  $\mathfrak{A}(\mathcal{O})$  of observables (a unital  **$C^*$ -algebra**) that can be measured in  $\mathcal{O}$ .
- The physical notion of subsystems is realized by the condition of **isotony**, i.e.:  $\mathcal{O}_1 \subset \mathcal{O}_2 \Rightarrow \mathfrak{A}(\mathcal{O}_1) \subset \mathfrak{A}(\mathcal{O}_2)$ . We obtain a **net of  $C^*$ -algebras**.



# Algebraic quantum field theory (locality)

- A convenient framework to investigate conceptual problems in QFT is the **Algebraic Quantum Field Theory**.
- It started as the axiomatic framework of **Haag-Kastler**: a model is defined by associating to each region  $\mathcal{O}$  of Minkowski spacetime an algebra  $\mathfrak{A}(\mathcal{O})$  of observables (a unital  **$C^*$ -algebra**) that can be measured in  $\mathcal{O}$ .
- The physical notion of subsystems is realized by the condition of **isotony**, i.e.:  $\mathcal{O}_1 \subset \mathcal{O}_2 \Rightarrow \mathfrak{A}(\mathcal{O}_1) \subset \mathfrak{A}(\mathcal{O}_2)$ . We obtain a **net of  $C^*$ -algebras**.
- Mathematically, AQFT makes use of **functional analysis** techniques (operator algebras), but its various generalizations involve many other branches of mathematics.

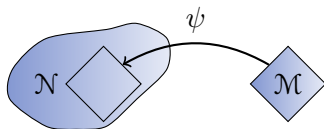
# Locally covariant quantum field theory

- To include effects of general relativity in QFT one has to be able to describe quantum fields on a general class of spacetimes. The corresponding generalization of the Haag-Kastler framework is called **locally covariant quantum field theory** and it uses the language of category theory.



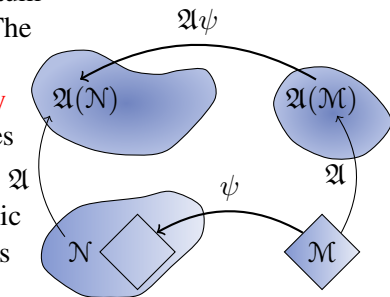
# Locally covariant quantum field theory

- To include effects of general relativity in QFT one has to be able to describe quantum fields on a general class of spacetimes. The corresponding generalization of the Haag-Kastler framework is called **locally covariant quantum field theory** and it uses the language of category theory.
- The category **Loc**, has globally hyperbolic spacetimes  $\mathcal{M} \doteq (M, g)$  as objects and its morphisms are isometric, orientations preserving, causal embeddings  $\psi : \mathcal{M} \rightarrow \mathcal{N}$ .



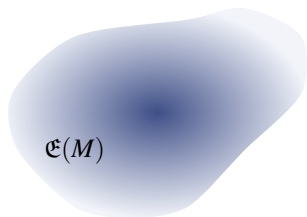
# Locally covariant quantum field theory

- To include effects of general relativity in QFT one has to be able to describe quantum fields on a general class of spacetimes. The corresponding generalization of the Haag-Kastler framework is called **locally covariant quantum field theory** and it uses the language of category theory.
- The category **Loc**, has globally hyperbolic spacetimes  $\mathcal{M} \doteq (M, g)$  as objects and its morphisms are isometric, orientations preserving, causal embeddings  $\psi : \mathcal{M} \rightarrow \mathcal{N}$ .
- A model in LCQFT is defined by giving a **functor**  $\mathfrak{A}$  from the category of spacetimes to the category **Obs** of observables (for example the category of  $C^*$ -algebras).



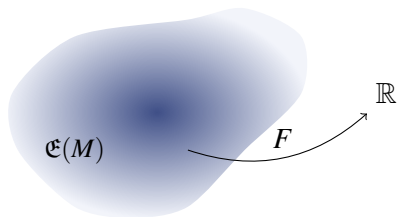
# Kinematical structure

- The **configuration space** (physical quantities we want to measure): space of smooth contravariant rank 2 tensors on  $M$ ,  $\mathfrak{E}(M) = \Gamma((T^*M)^{\otimes 2})$ .



# Kinematical structure

- The **configuration space** (physical quantities we want to measure): space of smooth contravariant rank 2 tensors on  $M$ ,  $\mathfrak{E}(M) = \Gamma((T^*M)^{\otimes 2})$ .
- **Observables**: smooth compactly supported multilocal functionals on  $\mathfrak{E}(M)$ . We denote this space by  $\mathfrak{F}(M)$ .  $\mathfrak{F}$  is a functor from **Loc** to **Vec** (the category of locally convex top. vector spaces).



# Kinematical structure

- The **configuration space** (physical quantities we want to measure): space of smooth contravariant rank 2 tensors on  $M$ ,  $\mathfrak{E}(\mathcal{M}) = \Gamma((T^*M)^{\otimes 2})$ .
- **Observables**: smooth compactly supported multilocal functionals on  $\mathfrak{E}(\mathcal{M})$ . We denote this space by  $\mathfrak{F}(\mathcal{M})$ .  $\mathfrak{F}$  is a functor from **Loc** to **Vec** (the category of locally convex top. vector spaces).
- To implement dynamics we use a certain generalization of the **Lagrange formalism** of classical mechanics.

# Kinematical structure

- The **configuration space** (physical quantities we want to measure): space of smooth contravariant rank 2 tensors on  $M$ ,  $\mathfrak{E}(\mathcal{M}) = \Gamma((T^*M)^{\otimes 2})$ .
- **Observables**: smooth compactly supported multilocal functionals on  $\mathfrak{E}(\mathcal{M})$ . We denote this space by  $\mathfrak{F}(\mathcal{M})$ .  $\mathfrak{F}$  is a functor from **Loc** to **Vec** (the category of locally convex top. vector spaces).
- To implement dynamics we use a certain generalization of the **Lagrange formalism** of classical mechanics.
- In general relativity we have the Einstein-Hilbert Lagrangian

$$L_{(M,g)}(f)[h] \doteq \int R[\tilde{g}]f \, d \operatorname{vol}_{(M,\tilde{g})}, \quad \tilde{g} = g + h.$$

# Kinematical structure

- The **configuration space** (physical quantities we want to measure): space of smooth contravariant rank 2 tensors on  $M$ ,  $\mathfrak{E}(\mathcal{M}) = \Gamma((T^*M)^{\otimes 2})$ .
- **Observables**: smooth compactly supported multilocal functionals on  $\mathfrak{E}(\mathcal{M})$ . We denote this space by  $\mathfrak{F}(\mathcal{M})$ .  $\mathfrak{F}$  is a functor from **Loc** to **Vec** (the category of locally convex top. vector spaces).
- To implement dynamics we use a certain generalization of the **Lagrange formalism** of classical mechanics.
- In general relativity we have the Einstein-Hilbert Lagrangian 
$$L_{(M,g)}(f)[h] \doteq \int R[\tilde{g}]f \, d \operatorname{vol}_{(M,\tilde{g})}, \quad \tilde{g} = g + h.$$
- We need the cutoff function  $f$  because  $M$  is **not compact**. The space of such test functions is denoted by  $\mathfrak{D}(\mathcal{M})$ .

# Kinematical structure

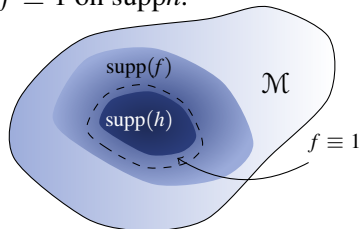
- The **configuration space** (physical quantities we want to measure): space of smooth contravariant rank 2 tensors on  $M$ ,  $\mathfrak{E}(\mathcal{M}) = \Gamma((T^*M)^{\otimes 2})$ .
- **Observables**: smooth compactly supported multilocal functionals on  $\mathfrak{E}(\mathcal{M})$ . We denote this space by  $\mathfrak{F}(\mathcal{M})$ .  $\mathfrak{F}$  is a functor from **Loc** to **Vec** (the category of locally convex top. vector spaces).
- To implement dynamics we use a certain generalization of the **Lagrange formalism** of classical mechanics.
- In general relativity we have the Einstein-Hilbert Lagrangian  $L_{(M,g)}(f)[h] \doteq \int R[\tilde{g}]f \, d \text{vol}_{(M,\tilde{g})}$ ,  $\tilde{g} = g + h$ .
- We need the cutoff function  $f$  because  $M$  is **not compact**. The space of such test functions is denoted by  $\mathfrak{D}(\mathcal{M})$ .
- The **action  $S(L)$**  is an equivalence class of Lagrangians, where  $L_1 \sim L_2$  if  $\text{supp}(L_{1,\mathcal{M}} - L_{2,\mathcal{M}})(f) \subset \text{supp}df \, \forall f \in \mathfrak{D}(\mathcal{M})$ .



# Dynamics and symmetries

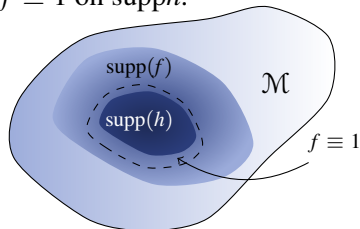
- The Euler-Lagrange derivative of  $S$  is defined by

$$\langle S'_{\mathcal{M}}(\tilde{g}), h \rangle = \langle S_{\mathcal{M}}(f)^{(1)}(\tilde{g}), h \rangle, \text{ where } f \equiv 1 \text{ on } \text{supp}h.$$



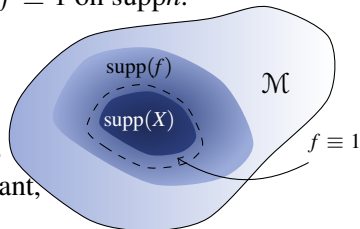
# Dynamics and symmetries

- The Euler-Lagrange derivative of  $S$  is defined by
 
$$\langle S'_{\mathcal{M}}(\tilde{g}), h \rangle = \langle S_{\mathcal{M}}(f)^{(1)}(\tilde{g}), h \rangle, \text{ where } f \equiv 1 \text{ on } \text{supp}h.$$
- Abstractly,  $S'_{\mathcal{M}}$  is a 1-form on  $\mathfrak{E}(\mathcal{M})$ .  
 The field equation is:  $S'_{\mathcal{M}}(\tilde{g}) = 0$ .



# Dynamics and symmetries

- The Euler-Lagrange derivative of  $S$  is defined by
 
$$\langle S'_M(\tilde{g}), h \rangle = \langle S_M(f)^{(1)}(\tilde{g}), h \rangle, \text{ where } f \equiv 1 \text{ on } \text{supp}h.$$
- Abstractly,  $S'_M$  is a 1-form on  $\mathfrak{E}(M)$ .  
 The field equation is:  $S'_M(\tilde{g}) = 0$ .
- A **symmetry** of  $S$  is a **vector field** on  $\mathfrak{E}(M)$ ,  $X \in \mathfrak{V}(M)$  that characterizes the direction in which  $S$  is locally constant, i.e.  $\forall \varphi \in \mathfrak{E}(M): \langle S'_M(\tilde{g}), X(\tilde{g}) \rangle = 0$ .



## Dynamics and symmetries

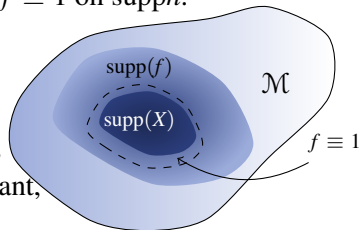
- The Euler-Lagrange derivative of  $S$  is defined by

$$\langle S'_M(\tilde{g}), h \rangle = \langle S_M(f)^{(1)}(\tilde{g}), h \rangle, \text{ where } f \equiv 1 \text{ on } \text{supp}h.$$

- Abstractly,  $S'_M$  is a 1-form on  $\mathfrak{E}(M)$ .

The field equation is:  $S'_M(\tilde{g}) = 0$ .

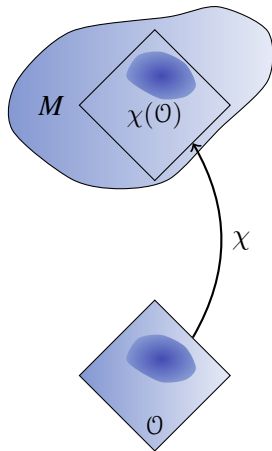
- A **symmetry** of  $S$  is a **vector field** on  $\mathfrak{E}(M)$ ,  $X \in \mathfrak{V}(M)$  that characterizes the direction in which  $S$  is locally constant, i.e.  $\forall \varphi \in \mathfrak{E}(M): \langle S'_M(\tilde{g}), X(\tilde{g}) \rangle = 0$ .



- Let  $\mathfrak{E}_S(M)$  denote the space of solutions to field equations. We want to characterise the space of functionals on  $\mathfrak{E}_S(M)$  which are invariant under all the local symmetries of  $S$ : **invariant on-shell functionals**  $\mathfrak{F}_S^{\text{inv}}(M)$ .

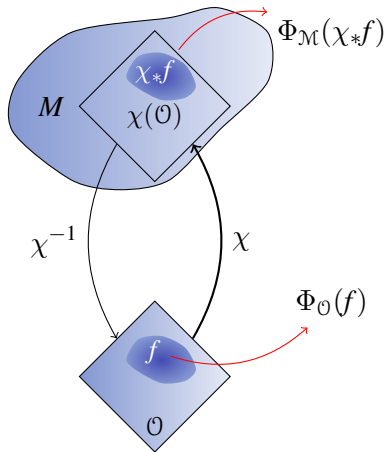
# Fields as natural transformations

- In the framework of locally covariant field theory [Brunetti-Fredenhagen-Verch 2003] fields are natural transformation between certain functors. Let  $\Phi \in \text{Nat}(\mathfrak{D}, \mathfrak{F})$  (both  $\mathfrak{D}$  and  $\mathfrak{F}$  are treated as functors into  $\text{Vec}$ ).



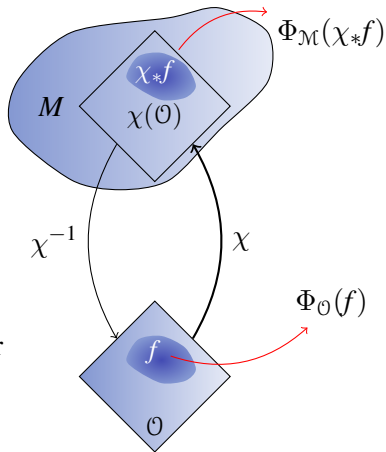
# Fields as natural transformations

- In the framework of locally covariant field theory [Brunetti-Fredenhagen-Verch 2003] fields are natural transformation between certain functors. Let  $\Phi \in \text{Nat}(\mathfrak{D}, \mathfrak{F})$  (both  $\mathfrak{D}$  and  $\mathfrak{F}$  are treated as functors into  $\text{Vec}$ ).
- The condition for  $\Phi$  to be a natural transformation:  $\Phi_{\mathcal{O}}(f)[\chi^*h] = \Phi_{\mathcal{M}}(\chi_*f)[h]$ .



# Fields as natural transformations

- In the framework of locally covariant field theory [Brunetti-Fredenhagen-Verch 2003] fields are natural transformation between certain functors. Let  $\Phi \in \text{Nat}(\mathfrak{D}, \mathfrak{F})$  (both  $\mathfrak{D}$  and  $\mathfrak{F}$  are treated as functors into  $\text{Vec}$ ).
- The condition for  $\Phi$  to be a natural transformation:  $\Phi_{\mathcal{O}}(f)[\chi^*h] = \Phi_{\mathcal{M}}(\chi_*f)[h]$ .
- In classical gravity we understand physical quantities not as pointwise objects but rather as something defined **on all the spacetimes in a coherent way**.



# Diffeomorphism invariance

- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}$ ,  $\xi_{\mathcal{M}} \in \Gamma_c(TM)$ .



# Diffeomorphism invariance

- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}$ ,  $\xi_{\mathcal{M}} \in \Gamma_c(TM)$ .
- After applying the exponential map we obtain  $\alpha_{\mathcal{M}} \doteq \exp(\xi_{\mathcal{M}})$ .

# Diffeomorphism invariance

- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}$ ,  $\xi_{\mathcal{M}} \in \Gamma_c(TM)$ .
- After applying the exponential map we obtain  $\alpha_{\mathcal{M}} \doteq \exp(\xi_{\mathcal{M}})$ .
- The exponentiated action of diffeomorphisms is given by:  
$$(\vec{\alpha}\Phi)_{(M,g)}(f)[\tilde{g}] = \Phi_{(M,g)}(\alpha_M^{-1} * f)[\alpha_M^* \tilde{g}].$$

# Diffeomorphism invariance

- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}$ ,  $\xi_{\mathcal{M}} \in \Gamma_c(TM)$ .
- After applying the exponential map we obtain  $\alpha_{\mathcal{M}} \doteq \exp(\xi_{\mathcal{M}})$ .
- The exponentiated action of diffeomorphisms is given by:  
 $(\vec{\alpha}\Phi)_{(M,g)}(f)[\tilde{g}] = \Phi_{(M,g)}(\alpha_M^{-1} * f)[\alpha_M^* \tilde{g}]$ .
- The derived action reads:

$$\begin{aligned} (\vec{\xi}\Phi)_{(M,g)}(f)[\tilde{g}] = \\ \left\langle (\Phi_{(M,g)}(f))^{(1)}[\tilde{g}], \mathcal{L}_{\xi_M} \tilde{g} \right\rangle + \Phi_{(M,g)}(\mathcal{L}_{\xi_M} f)[\tilde{g}]. \end{aligned}$$

# Diffeomorphism invariance

- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}$ ,  $\xi_{\mathcal{M}} \in \Gamma_c(TM)$ .
- After applying the exponential map we obtain  $\alpha_{\mathcal{M}} \doteq \exp(\xi_{\mathcal{M}})$ .
- The exponentiated action of diffeomorphisms is given by:  
 $(\vec{\alpha}\Phi)_{(M,g)}(f)[\tilde{g}] = \Phi_{(M,g)}(\alpha_M^{-1} * f)[\alpha_M^* \tilde{g}]$ .
- The derived action reads:  
 $(\vec{\xi}\Phi)_{(M,g)}(f)[\tilde{g}] =$   
 $\left\langle (\Phi_{(M,g)}(f))^{(1)}[\tilde{g}], \mathcal{L}_{\xi_M} \tilde{g} \right\rangle + \Phi_{(M,g)}(\mathcal{L}_{\xi_M} f)[\tilde{g}].$
- Diffeomorphism invariance is the statement that  $\vec{\xi}\Phi = 0$ .

## Diffeomorphism invariance

- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}$ ,  $\xi_{\mathcal{M}} \in \Gamma_c(TM)$ .
- After applying the exponential map we obtain  $\alpha_{\mathcal{M}} \doteq \exp(\xi_{\mathcal{M}})$ .
- The exponentiated action of diffeomorphisms is given by:  $(\vec{\alpha}\Phi)_{(M,g)}(f)[\tilde{g}] = \Phi_{(M,g)}(\alpha_M^{-1} * f)[\alpha_M^* \tilde{g}]$ .
- The derived action reads:  $(\vec{\xi}\Phi)_{(M,g)}(f)[\tilde{g}] = \left\langle (\Phi_{(M,g)}(f))^{(1)}[\tilde{g}], \mathcal{L}_{\xi_M} \tilde{g} \right\rangle + \Phi_{(M,g)}(\mathcal{L}_{\xi_M} f)[\tilde{g}]$ .
- Diffeomorphism invariance is the statement that  $\vec{\xi}\Phi = 0$ .
- Example:  $\int R[\tilde{g}]f \, d \text{vol}_{(M,\tilde{g})}$  is diffeomorphism invariant, but  $\int R[\tilde{g}]f \, d \text{vol}_{(M,g)}$  is not.

## Physical interpretation

- Let us fix  $\mathcal{M}$ . A test tensor  $f \in \mathcal{Tens}_c(\mathcal{M})$  corresponds to a concrete geometrical setting of an experiment, so for each  $\mathcal{M} \in \mathbf{Obj}(\mathbf{Loc})$ , we obtain a functional  $\Phi(f)$ , which depends covariantly on the geometrical data provided by  $f$ .

## Physical interpretation

- Let us fix  $\mathcal{M}$ . A test tensor  $f \in \mathfrak{Tens}_c(\mathcal{M})$  corresponds to a concrete geometrical setting of an experiment, so for each  $\mathcal{M} \in \text{Obj}(\mathbf{Loc})$ , we obtain a functional  $\Phi(f)$ , which depends covariantly on the geometrical data provided by  $f$ .
- Given  $f \in \mathfrak{Tens}_c(\mathcal{M})$  we recover not only the functional  $\Phi_{\mathcal{M}}(f)$ , but also the whole **diffeomorphism class of functionals**  $\Phi_{\mathcal{M}}(\alpha_* f)$ , where  $\alpha \in \text{Diff}_c(\mathcal{M})$ .

## Physical interpretation

- Let us fix  $\mathcal{M}$ . A test tensor  $f \in \mathfrak{Tens}_c(\mathcal{M})$  corresponds to a concrete geometrical setting of an experiment, so for each  $\mathcal{M} \in \text{Obj}(\mathbf{Loc})$ , we obtain a functional  $\Phi(f)$ , which depends covariantly on the geometrical data provided by  $f$ .
- Given  $f \in \mathfrak{Tens}_c(\mathcal{M})$  we recover not only the functional  $\Phi_{\mathcal{M}}(f)$ , but also the whole **diffeomorphism class of functionals**  $\Phi_{\mathcal{M}}(\alpha_* f)$ , where  $\alpha \in \text{Diff}_c(\mathcal{M})$ .
- We allow arbitrary tensors to be test objects, because we don't want to restrict a priori possible experimental settings.



## Physical interpretation

- Let us fix  $\mathcal{M}$ . A test tensor  $f \in \mathfrak{Tens}_c(\mathcal{M})$  corresponds to a concrete geometrical setting of an experiment, so for each  $\mathcal{M} \in \text{Obj}(\mathbf{Loc})$ , we obtain a functional  $\Phi(f)$ , which depends covariantly on the geometrical data provided by  $f$ .
- Given  $f \in \mathfrak{Tens}_c(\mathcal{M})$  we recover not only the functional  $\Phi_{\mathcal{M}}(f)$ , but also the whole **diffeomorphism class of functionals**  $\Phi_{\mathcal{M}}(\alpha_* f)$ , where  $\alpha \in \text{Diff}_c(\mathcal{M})$ .
- We allow arbitrary tensors to be test objects, because we don't want to restrict a priori possible experimental settings.

### New insight

Classical (or quantum) fields **generate physical quantities**, but a concrete observable quantity is obtained by evaluation on a test tensor. New concept: **evaluated fields**.

# Evaluation of fields

- In our formalism, the full information about the dependence of a measurement on the geometrical setup should be contained in the family  $(\alpha_* f)_{\alpha \in \text{Diff}_c(\mathcal{M})}$ .

# Evaluation of fields

- In our formalism, the full information about the dependence of a measurement on the geometrical setup should be contained in the family  $(\alpha_* f)_{\alpha \in \text{Diff}_c(\mathcal{M})}$ .
- Therefore, for a fixed  $\mathcal{M}$  and  $\Phi$ , a physically meaningful object is the function  $\Phi_f : \text{Diff}_c(\mathcal{M}) \ni \alpha \mapsto \Phi_{\mathcal{M}}(\alpha_* f)$ .

# Evaluation of fields

- In our formalism, the full information about the dependence of a measurement on the geometrical setup should be contained in the family  $(\alpha_* f)_{\alpha \in \text{Diff}_c(\mathcal{M})}$ .
- Therefore, for a fixed  $\mathcal{M}$  and  $\Phi$ , a physically meaningful object is the function  $\Phi_f : \text{Diff}_c(\mathcal{M}) \ni \alpha \mapsto \Phi_{\mathcal{M}}(\alpha_* f)$ .
- Let  $\mathcal{F}$  denote the subspace of  $\mathcal{C}^\infty(\text{Diff}_c(\mathcal{M}), \mathfrak{F}(\mathcal{M}))$  generated by elements of the form  $\Phi_f$  with respect to the pointwise product.

# Evaluation of fields

- In our formalism, the full information about the dependence of a measurement on the geometrical setup should be contained in the family  $(\alpha_* f)_{\alpha \in \text{Diff}_c(\mathcal{M})}$ .
- Therefore, for a fixed  $\mathcal{M}$  and  $\Phi$ , a physically meaningful object is the function  $\Phi_f : \text{Diff}_c(\mathcal{M}) \ni \alpha \mapsto \Phi_{\mathcal{M}}(\alpha_* f)$ .
- Let  $\mathcal{F}$  denote the subspace of  $\mathcal{C}^\infty(\text{Diff}_c(\mathcal{M}), \mathfrak{F}(\mathcal{M}))$  generated by elements of the form  $\Phi_f$  with respect to the pointwise product.
- This notion of observables corresponds to partial (relative) observables of Rovelli, Dittrich and Thiemann.

# BV complex

- A general method to quantize theories with local symmetries is the so called Batalin-Vilkovisky (BV) formalism. Here we present its version proposed by [K. Fredenhagen, K.R., CMP 2011].

# BV complex

- A general method to quantize theories with local symmetries is the so called Batalin-Vilkovisky (BV) formalism. Here we present its version proposed by [K. Fredenhagen, K.R., CMP 2011].
- The space of **on-shell functionals** is a quotient of  $\mathcal{F}$  by the ideal generated by  $S'_{\mathcal{M}}(\tilde{g})$  and can be described as a homology of the **Koszul-Tate complex**.

# BV complex

- A general method to quantize theories with local symmetries is the so called Batalin-Vilkovisky (BV) formalism. Here we present its version proposed by [K. Fredenhagen, K.R., CMP 2011].
- The space of **on-shell functionals** is a quotient of  $\mathcal{F}$  by the ideal generated by  $S'_{\mathcal{M}}(\tilde{g})$  and can be described as a homology of the **Koszul-Tate complex**.
- The space of **invariants** under a Lie algebra action can be seen as the 0 cohomology of the **Chevalley-Eilenberg complex**.



# BV complex

- A general method to quantize theories with local symmetries is the so called Batalin-Vilkovisky (BV) formalism. Here we present its version proposed by [K. Fredenhagen, K.R., CMP 2011].
- The space of **on-shell functionals** is a quotient of  $\mathcal{F}$  by the ideal generated by  $S'_{\mathcal{M}}(\tilde{g})$  and can be described as a homology of the **Koszul-Tate complex**.
- The space of **invariants** under a Lie algebra action can be seen as the 0 cohomology of the **Chevalley-Eilenberg complex**.
- We can combine the Koszul-Tate complex and the Chevalley-Eilenberg complex to a **BV (Batalin-Vilkovisky) bicomplex**, whose 0th cohomology characterizes  $\mathcal{F}_S^{\text{inv}}$  (the space of gauge-invariant, on-shell evaluated fields).

# BV complex

- A general method to quantize theories with local symmetries is the so called Batalin-Vilkovisky (BV) formalism. Here we present its version proposed by [K. Fredenhagen, K.R., CMP 2011].
- The space of **on-shell functionals** is a quotient of  $\mathcal{F}$  by the ideal generated by  $S'_{\mathcal{M}}(\tilde{g})$  and can be described as a homology of the **Koszul-Tate complex**.
- The space of **invariants** under a Lie algebra action can be seen as the 0 cohomology of the **Chevalley-Eilenberg complex**.
- We can combine the Koszul-Tate complex and the Chevalley-Eilenberg complex to a **BV (Batalin-Vilkovisky) bicomplex**, whose 0th cohomology characterizes  $\mathcal{F}_S^{\text{inv}}$  (the space of gauge-invariant, on-shell evaluated fields).
- The underlying algebra of the BV complex is a graded algebra denoted by  $\mathcal{BV}$ .

# BV complex

- $\mathcal{BV}$  is geometrically interpreted as a subalgebra of the space of smooth functions on  $\text{Diff}_c(\mathcal{M})$  with values in multivector fields on some graded manifold  $\overline{\mathcal{E}}(\mathcal{M})$ . We can equip the space of multivector fields with the Schouten bracket:

# BV complex

- $\mathcal{BV}$  is geometrically interpreted as a subalgebra of the space of smooth functions on  $\text{Diff}_c(\mathcal{M})$  with values in multivector fields on some graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$ . We can equip the space of multivector fields with the Schouten bracket:
  - $\{X, F\} = \partial_X F$  for  $X$  a vector field and  $F$  function,

# BV complex

- $\mathcal{BV}$  is geometrically interpreted as a subalgebra of the space of smooth functions on  $\text{Diff}_c(\mathcal{M})$  with values in multivector fields on some graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$ . We can equip the space of multivector fields with the Schouten bracket:
  - $\{X, F\} = \partial_X F$  for  $X$  a vector field and  $F$  function,
  - $\{X, Y\} = [X, Y]$  for  $X, Y$  a vector fields,

# BV complex

- $\mathcal{BV}$  is geometrically interpreted as a subalgebra of the space of smooth functions on  $\text{Diff}_c(\mathcal{M})$  with values in multivector fields on some graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$ . We can equip the space of multivector fields with the Schouten bracket:
  - $\{X, F\} = \partial_X F$  for  $X$  a vector field and  $F$  function,
  - $\{X, Y\} = [X, Y]$  for  $X, Y$  a vector fields,
  - graded Leibniz rule.

# BV complex

- $\mathcal{BV}$  is geometrically interpreted as a subalgebra of the space of smooth functions on  $\text{Diff}_c(\mathcal{M})$  with values in multivector fields on some graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$ . We can equip the space of multivector fields with the Schouten bracket:
  - $\{X, F\} = \partial_X F$  for  $X$  a vector field and  $F$  function,
  - $\{X, Y\} = [X, Y]$  for  $X, Y$  a vector fields,
  - graded Leibniz rule.
- This induces a graded Poisson bracket  $\{.,.\}$  on  $\mathcal{BV}$ . The BV-differential on  $\mathcal{BV}$  is given by:  
 $(s\Phi)_{\mathcal{M}}(f) = \{\Phi_{\mathcal{M}}(f), S + \gamma\} + \Phi_{\mathcal{M}}(\mathcal{L}_C f)$ ,  
where  $C \in \mathfrak{X}(M)$  is the ghost and  $\gamma$  is the Chevalley-Eilenberg differential, which acts on  $\mathcal{BV}$  via infinitesimal diffeomorphism transformations along the ghost fields  $C$ .

# BV complex

- $\mathcal{BV}$  is geometrically interpreted as a subalgebra of the space of smooth functions on  $\text{Diff}_c(\mathcal{M})$  with values in multivector fields on some graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$ . We can equip the space of multivector fields with the Schouten bracket:
  - $\{X, F\} = \partial_X F$  for  $X$  a vector field and  $F$  function,
  - $\{X, Y\} = [X, Y]$  for  $X, Y$  a vector fields,
  - graded Leibniz rule.
- This induces a graded Poisson bracket  $\{., .\}$  on  $\mathcal{BV}$ . The BV-differential on  $\mathcal{BV}$  is given by:  
 $(s\Phi)_{\mathcal{M}}(f) = \{\Phi_{\mathcal{M}}(f), S + \gamma\} + \Phi_{\mathcal{M}}(\mathcal{L}_C f)$ ,  
where  $C \in \mathfrak{X}(M)$  is the ghost and  $\gamma$  is the Chevalley-Eilenberg differential, which acts on  $\mathcal{BV}$  via infinitesimal diffeomorphism transformations along the ghost fields  $C$ .
- Gauge invariant observables are given by:  $\mathcal{F}_S^{\text{inv}} := H^0(s, \mathcal{BV})$ .



# Gauge fixing

- Gauge fixing is implemented by means of the so called gauge fixing fermion  $\Psi_f \in \mathcal{BV}$  with ghost number  $\#gh = 1$ .

# Gauge fixing

- Gauge fixing is implemented by means of the so called gauge fixing fermion  $\Psi_f \in \mathcal{BV}$  with ghost number  $\#gh = 1$ .
- We define an automorphism of  $\mathcal{BV}$  by

$$\alpha_{\Psi}(X) := \sum_{n=0}^{\infty} \frac{1}{n!} \underbrace{\{\Psi_f, \dots, \{\Psi_f, X\} \dots\}}_n,$$

where  $f \equiv 1$  on the support of  $X$ .

# Gauge fixing

- Gauge fixing is implemented by means of the so called gauge fixing fermion  $\Psi_f \in \mathcal{BV}$  with ghost number  $\#gh = 1$ .
- We define an automorphism of  $\mathcal{BV}$  by

$$\alpha_\Psi(X) := \sum_{n=0}^{\infty} \frac{1}{n!} \underbrace{\{\Psi_f, \dots, \{\Psi_f, X\} \dots\}}_n,$$

where  $f \equiv 1$  on the support of  $X$ .

- We obtain a new extended action  $\tilde{S} \doteq \alpha_\Psi(S + \gamma)$  and gauge-fixed BV differential  $s^\Psi = \alpha_\Psi \circ s \circ \alpha_\Psi^{-1}$

# Gauge fixing

- Gauge fixing is implemented by means of the so called gauge fixing fermion  $\Psi_f \in \mathcal{BV}$  with ghost number  $\#gh = 1$ .
- We define an automorphism of  $\mathcal{BV}$  by

$$\alpha_\Psi(X) := \sum_{n=0}^{\infty} \frac{1}{n!} \underbrace{\{\Psi_f, \dots, \{\Psi_f, X\} \dots\}}_n,$$

where  $f \equiv 1$  on the support of  $X$ .

- We obtain a new extended action  $\tilde{S} \doteq \alpha_\Psi(S + \gamma)$  and gauge-fixed BV differential  $s^\Psi = \alpha_\Psi \circ s \circ \alpha_\Psi^{-1}$
- Note that  $H^0(s^\Psi, \alpha_\Psi(\mathcal{BV})) = H^0(s, \mathcal{BV}) = \mathcal{F}_S^{\text{inv}}$ .

# Equations of motion and Poisson bracket

- As an output of classical field theory we have a graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$  and an extended action  $\tilde{S}$ . Now we apply to this data the deformation quantization.

# Equations of motion and Poisson bracket

- As an output of classical field theory we have a graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$  and an extended action  $\tilde{S}$ . Now we apply to this data the deformation quantization.
- We can Taylor expand the gauge fixed action around an arbitrary background metric  $g$  and obtain  $\tilde{S} = S_0^g + V^g$ , where  $S_0^g$  is at most quadratic in fields and has  $\#_{\text{af}} = 0$ .

# Equations of motion and Poisson bracket

- As an output of classical field theory we have a graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$  and an extended action  $\tilde{S}$ . Now we apply to this data the deformation quantization.
- We can Taylor expand the gauge fixed action around an arbitrary background metric  $g$  and obtain  $\tilde{S} = S_0^g + V^g$ , where  $S_0^g$  is at most quadratic in fields and has  $\#af = 0$ .
- For each globally hyperbolic background  $g$ , we have the retarded and advanced Green's functions  $\Delta_g^{R/A}$  for the EOM's derived from  $S_0^g$ .

# Equations of motion and Poisson bracket

- As an output of classical field theory we have a graded manifold  $\overline{\mathfrak{E}}(\mathcal{M})$  and an extended action  $\tilde{S}$ . Now we apply to this data the deformation quantization.
- We can Taylor expand the gauge fixed action around an arbitrary background metric  $g$  and obtain  $\tilde{S} = S_0^g + V^g$ , where  $S_0^g$  is at most quadratic in fields and has  $\#af = 0$ .
- For each globally hyperbolic background  $g$ , we have the retarded and advanced Green's functions  $\Delta_g^{R/A}$  for the EOM's derived from  $S_0^g$ .
- Using this input, we define the free Poisson bracket on  $\mathcal{BV}$

$$\{F, G\}_0^g \doteq \left\langle F^{(1)}, \Delta_g G^{(1)} \right\rangle \quad \Delta_g = \Delta_g^R - \Delta_g^A,$$



# Deformation quantization

- We start with the deformation quantization of  $(\mathcal{BV}, \{.,.\}_0)$ .

# Deformation quantization

- We start with the deformation quantization of  $(\mathcal{BV}, \{.,.\}_0)$ .
- We need to include into the space of functionals on  $\overline{\mathcal{E}}(\mathcal{M})$  some more singular objects. The right notion of regularity is related to a certain wavefront set property of Hadamard 2-point functions (microlocal spectrum condition,  $\mu\text{SC}$ ). The resulting space will be denoted by  $\mathcal{BV}_{\mu\text{c}}$ .

# Deformation quantization

- We start with the deformation quantization of  $(\mathcal{BV}, \{.,.\}_0)$ .
- We need to include into the space of functionals on  $\overline{\mathcal{E}}(\mathcal{M})$  some more singular objects. The right notion of regularity is related to a certain wavefront set property of Hadamard 2-point functions (microlocal spectrum condition,  $\mu\text{SC}$ ). The resulting space will be denoted by  $\mathcal{BV}_{\mu\text{C}}$ .
- The deformation quantization of  $(\mathcal{BV}_{\mu\text{C}}, \{.,.\}_0^g)$  can be performed in the standard way, by introducing a  $\star$ -product:

$$(F \star_H G) \doteq m \circ \exp(\hbar\Gamma_{\omega_H})(F \otimes G) ,$$

where  $\Gamma_{\omega_H} \doteq \int dx dy \omega_H(x, y) \frac{\delta}{\delta\varphi(x)} \otimes \frac{\delta}{\delta\varphi(y)}$  and

$\omega_H = \frac{i}{2}\Delta_g + H$  is the Hadamard 2-point function (satisfies the linearized EOM's in both arguments and the  $\mu\text{SC}$ ).

# Deformation quantization

- For a fixed  $\mathcal{M}$  we have a family of algebras  $\mathfrak{A}_H(\mathcal{M}) = (\mathcal{BV}_{\mu c}[[\hbar, \lambda]], \star_H)$ , numbered by possible choices of  $H$ . We can define  $\mathfrak{A}(\mathcal{M})$  to be an algebra consisting of families  $(F_H)$ , such that  $F_H = e^{\frac{\hbar}{2}\Gamma'_{H-H'}} F_{H'}$ , where  $\Gamma'_{H-H'} \doteq \int dx dy (H - H')(x, y) \frac{\delta^2}{\delta\varphi(x)\delta\varphi(y)}$  and the star product is given by

$$(F \star G)_H \doteq F_H \star_H G_H.$$

# Deformation quantization

- For a fixed  $\mathcal{M}$  we have a family of algebras  $\mathfrak{A}_H(\mathcal{M}) = (\mathcal{BV}_{\mu c}[[\hbar, \lambda]], \star_H)$ , numbered by possible choices of  $H$ . We can define  $\mathfrak{A}(\mathcal{M})$  to be an algebra consisting of families  $(F_H)$ , such that  $F_H = e^{\frac{\hbar}{2}\Gamma'_{H-H'}} F_{H'}$ , where

$\Gamma'_{H-H'} \doteq \int dx dy (H - H')(x, y) \frac{\delta^2}{\delta\varphi(x)\delta\varphi(y)}$  and the star product is given by

$$(F \star G)_H \doteq F_H \star_H G_H.$$

- This leads to a deformation quantization  $(\mathfrak{A}(\mathcal{M}), \star)$  of the space of evaluated fields.

# Interaction

- In the next step we have to introduce the interaction, i.e. consider the algebras  $\mathfrak{A}_H(\mathcal{M}) = (\mathcal{BV}_{\mu c}[[\hbar, \lambda]], \star_H)$  and define on them the renormalized time-ordered products  $\cdot_{\mathcal{T}_H}$  by the Epstein-Glaser method.

# Interaction

- In the next step we have to introduce the interaction, i.e. consider the algebras  $\mathfrak{A}_H(\mathcal{M}) = (\mathcal{BV}_{\mu c}[[\hbar, \lambda]], \star_H)$  and define on them the renormalized time-ordered products  $\cdot_{\mathcal{T}_H}$  by the Epstein-Glaser method.
- Products  $\cdot_{\mathcal{T}_H}$  induce a product  $\cdot_{\mathcal{T}}$  on  $\mathfrak{A}(\mathcal{M})$ . The formal S-matrix is given by:  $\mathcal{S}(V^g) \doteq e_{\mathcal{T}}^{V^g}$ .

# Interaction

- In the next step we have to introduce the interaction, i.e. consider the algebras  $\mathfrak{A}_H(\mathcal{M}) = (\mathcal{BV}_{\mu c}[[\hbar, \lambda]], \star_H)$  and define on them the renormalized time-ordered products  $\cdot_{\mathcal{T}_H}$  by the Epstein-Glaser method.
- Products  $\cdot_{\mathcal{T}_H}$  induce a product  $\cdot_{\mathcal{T}}$  on  $\mathfrak{A}(\mathcal{M})$ . The formal S-matrix is given by:  $\mathcal{S}(V^g) \doteq e_{\mathcal{T}}^{V^g}$ .
- Interacting fields are obtained from free ones by the Bogoliubov formula:

$$(R_V(\Phi))_{\mathcal{M}}(f) \doteq \left. \frac{d}{dt} \right|_{t=0} \mathcal{S}(V^g)^{\star-1} \star \mathcal{S}(V^g + t\Phi_{\mathcal{M}}(f)).$$



# Quantum observables

- In the framework of [K. Fredenhagen, K.R., CMP 2013], the  $S$ -matrix has to satisfy the so called quantum master equation (QME):

$$\{e_{\mathcal{T}}^{V^g}, S_0^g\} = 0.$$

## Quantum observables

- In the framework of [K. Fredenhagen, K.R., CMP 2013], the  $S$ -matrix has to satisfy the so called quantum master equation (QME):

$$\{e_{\mathcal{T}}^{V^g}, S_0^g\} = 0.$$

- With the use of Master Ward Identity [F.Brennecke, M.Duetsch, RMP 2008], this condition can be rewritten as

$$\frac{1}{2}\{S_0^g + V^g, S_0^g + V^g\} = i\hbar\Delta_{V^g},$$

where  $\Delta_{V^g}$  is the anomaly.

# Quantum observables

- In the framework of [K. Fredenhagen, K.R., CMP 2013], the  $S$ -matrix has to satisfy the so called quantum master equation (QME):

$$\{e_{\mathcal{T}}^{V^g}, S_0^g\} = 0.$$

- With the use of Master Ward Identity [F.Brennecke, M.Duetsch, RMP 2008], this condition can be rewritten as

$$\frac{1}{2}\{S_0^g + V^g, S_0^g + V^g\} = i\hbar\Delta_{V^g},$$

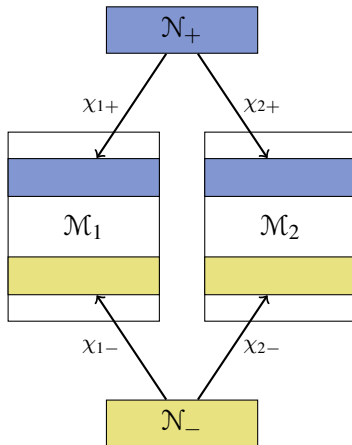
where  $\Delta_{V^g}$  is the anomaly.

- If the QME holds, then gauge invariant quantum observables are recovered as the 0th cohomology of the quantum BV operator  $\hat{s} \doteq R_V^{-1} \circ \{., S_0\} \circ R_V$ . Equivalently,

$$\hat{s}\Phi_{\mathcal{M}}(f) = \{., S_0^g + V^g\} + \Phi_{\mathcal{M}}(\mathcal{L}_C f) - i\hbar \Delta_{V^g} (\Phi_{\mathcal{M}}(f)).$$

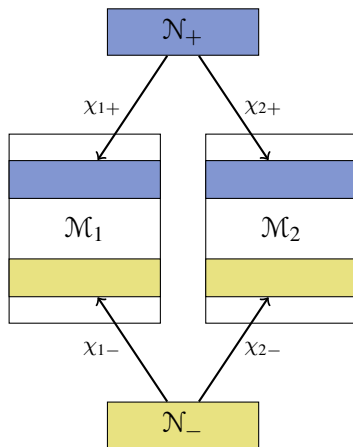
# Relative Cauchy evolution

- Let  $\mathcal{N}_+$  and  $\mathcal{N}_-$  be two spacetimes that embed into two other spacetimes  $\mathcal{M}_1$  and  $\mathcal{M}_2$  around Cauchy surfaces, via causal embeddings given by  $\chi_{k,\pm}$ ,  $k = 1, 2$ .



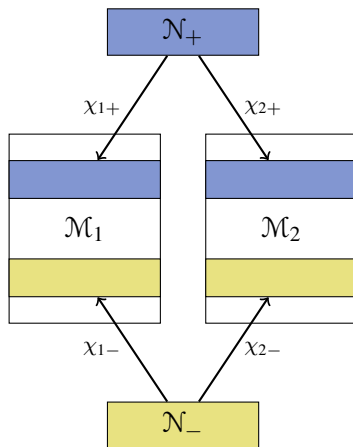
# Relative Cauchy evolution

- Let  $\mathcal{N}_+$  and  $\mathcal{N}_-$  be two spacetimes that embed into two other spacetimes  $\mathcal{M}_1$  and  $\mathcal{M}_2$  around Cauchy surfaces, via causal embeddings given by  $\chi_{k,\pm}$ ,  $k = 1, 2$ .
- Then  $\beta = \alpha_{\chi_{1+}} \alpha_{\chi_{2+}}^{-1} \alpha_{\chi_{2-}} \alpha_{\chi_{1-}}^{-1}$  is an automorphism of  $\mathfrak{A}(\mathcal{M}_1)$ .



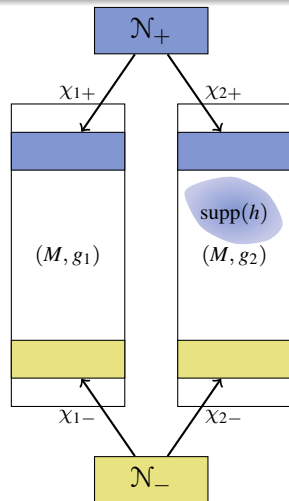
# Relative Cauchy evolution

- Let  $\mathcal{N}_+$  and  $\mathcal{N}_-$  be two spacetimes that embed into two other spacetimes  $\mathcal{M}_1$  and  $\mathcal{M}_2$  around Cauchy surfaces, via causal embeddings given by  $\chi_{k,\pm}$ ,  $k = 1, 2$ .
- Then  $\beta = \alpha_{\chi_{1+}} \alpha_{\chi_{2+}}^{-1} \alpha_{\chi_{2-}} \alpha_{\chi_{1-}}^{-1}$  is an automorphism of  $\mathfrak{A}(\mathcal{M}_1)$ .
- It depends only on the spacetime between the two Cauchy surfaces



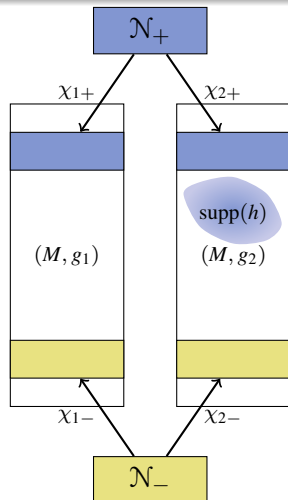
# Background independence

- Let  $\mathcal{M}_1 = (M, g_1)$  and  $\mathcal{M}_2 = (M, g_2)$ , where  $(g_1)_{\mu\nu}$  and  $(g_2)_{\mu\nu}$  differ by a (compactly supported) symmetric tensor  $h_{\mu\nu}$  with  $\text{supp}(h) \cap J^+(\mathcal{N}_+) \cap J^-(\mathcal{N}_-) = \emptyset$ ,



# Background independence

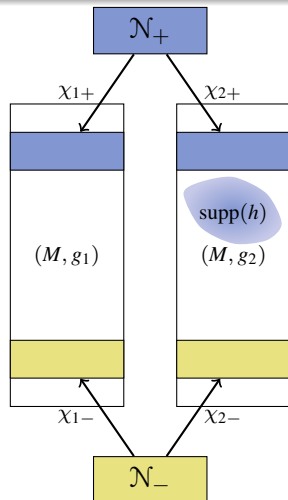
- Let  $\mathcal{M}_1 = (M, g_1)$  and  $\mathcal{M}_2 = (M, g_2)$ , where  $(g_1)_{\mu\nu}$  and  $(g_2)_{\mu\nu}$  differ by a (compactly supported) symmetric tensor  $h_{\mu\nu}$  with  $\text{supp}(h) \cap J^+(\mathcal{N}_+) \cap J^-(\mathcal{N}_-) = \emptyset$ ,
- $\Theta_{\mu\nu}(x) \doteq \left. \frac{\delta\beta_h}{\delta h_{\mu\nu}(x)} \right|_{h=0}$  is a derivation valued distribution which is covariantly conserved.





# Background independence

- Let  $\mathcal{M}_1 = (M, g_1)$  and  $\mathcal{M}_2 = (M, g_2)$ , where  $(g_1)_{\mu\nu}$  and  $(g_2)_{\mu\nu}$  differ by a (compactly supported) symmetric tensor  $h_{\mu\nu}$  with  $\text{supp}(h) \cap J^+(\mathcal{N}_+) \cap J^-(\mathcal{N}_-) = \emptyset$ ,
- $\Theta_{\mu\nu}(x) \doteq \left. \frac{\delta\beta_h}{\delta h_{\mu\nu}(x)} \right|_{h=0}$  is a derivation valued distribution which is covariantly conserved.
- The infinitesimal version of the background independence is condition reads:  $\Theta_{\mu\nu} = 0$ .



# Background independence

Theorem [Brunetti, Fredenhagen, K.R. 2013]

The functional derivative  $\Theta_{\mu\nu}$  of the relative Cauchy evolution can be expressed as

$$\Theta_{\mu\nu}(\Phi_{\mathcal{M}_1}(f)) \stackrel{o.s.}{=} [R_{V_1}(\Phi_{\mathcal{M}_1}(f)), R_{V_1}(T_{\mu\nu})]_{\star},$$

where  $T_{\mu\nu}$  is the stress-energy tensor of the extended action and one can define the time-ordered products in such a way that  $T_{\mu\nu} = 0$  holds, so the interacting theory is background independent.

# Conclusions

- We have constructed a consistent model of perturbative quantum gravity within the framework of locally covariant quantum fields theory.

# Conclusions

- We have constructed a consistent model of perturbative quantum gravity within the framework of locally covariant quantum fields theory.
- In our framework, physical diffeomorphism invariant quantities are constructed as natural transformations between certain functors. We have proposed a quantization prescription for such objects, which makes use of the BV formalism.

# Conclusions

- We have constructed a consistent model of perturbative quantum gravity within the framework of locally covariant quantum fields theory.
- In our framework, physical diffeomorphism invariant quantities are constructed as natural transformations between certain functors. We have proposed a quantization prescription for such objects, which makes use of the BV formalism.
- To quantize the theory, we make a tentative split into a free and interacting theory. We quantize the free theory first and then use the Epstein-Glaser renormalization to introduce the interaction.

# Conclusions

- We have constructed a consistent model of perturbative quantum gravity within the framework of locally covariant quantum fields theory.
- In our framework, physical diffeomorphism invariant quantities are constructed as natural transformations between certain functors. We have proposed a quantization prescription for such objects, which makes use of the BV formalism.
- To quantize the theory, we make a tentative split into a free and interacting theory. We quantize the free theory first and then use the Epstein-Glaser renormalization to introduce the interaction.
- We have shown, using the relative Cauchy evolution, that our theory is background independent, i.e. independent of the split into free and interacting part.



Thank you for your attention!